

Mr Mohit Tiwari et al.,(2017) stated that Intrusion Detection System (IDS) defined as a Device or software application which monitors the network or system activities and finds if there is any malicious activity occurs. The main objective of this research study is to provide a complete study about the intrusion detection, types of intrusion detection methods, types of attacks, different tools and techniques, research needs, challenges and finally develop the IDS Tool for Research Purpose That tool are capable of detect and prevent the intrusion from the intruder[19].

Rajni Tewatia, and Asha Mishra(2015) emphasized that Security of a network is always an important issue. With the continuously growing network, the basic security such as firewall, virus scanner is easily deceived by modern attackers who are experts in using software vulnerabilities to achieve their goals. For preventing such attacks, we need even smarter security mechanism which act proactively and intelligently. Intrusion Detection System is the solution of such requirement. Many techniques have been used to implement IDS. This technique basically used in the detector part of IDS such as Neural Network, Clustering, Pattern Matching, Rule Based, Fuzzy Logic, Genetic Algorithms and many more[20].

The effectiveness of deep learning, in particular Convolutional Neural Networks (CNNs), in improving intrusion detection systems (IDS) has been highlighted by recent studies. Numerous studies demonstrate how CNNs can automatically extract intricate features from unprocessed network traffic, improving real-time performance and detection accuracy [21], [22], and [23]. By successfully detecting different attack patterns and anomalies across a range of environments, including IoT networks [24] and general cybersecurity applications [25], these models outperform conventional techniques. Furthermore, feature extraction research highlights that CNNs improve classification reliability while lowering manual labor, which makes them ideal for changing cyber threats [26], [27].

The convergence of these studies shows generally that CNN-based methods are interesting tools for producing strong, scalable, and efficient IDS solutions. Emphasizing their ability to detect complex attack patterns and anomalies in network traffic, the application of deep neural networks including CNN architectures keeps expanding inside cybersecurity research. By properly capturing spatial and temporal elements, CNNs can enhance detection performance and reduce reliance on hand feature engineering [28], [29]. CNN-based models can automatically learn pertinent indicators of intrusion, so enabling faster and more accurate classification even in noisy or complex datasets [30], [31], according to research concentrated on feature extraction techniques. These developments help deep learning models capable of changing to fit changing cyber threats and offering scalable security solutions.

OBJECTIVES

The researchers formulated the following objectives for a study on a CNN-based Deep Learning Model for Intrusion Detection System (IDS) aimed at improving high accuracy on Big Data:

1. To analyze the limitations of traditional and machine learning-based intrusion detection systems in handling large-scale network traffic data.
2. To design and develop a Convolutional Neural Network (CNN)-based deep learning model optimized for intrusion detection in big data environments.
3. To enhance the accuracy and detection rate of the IDS by leveraging spatial feature extraction capabilities of CNN architectures.

METHODS

The learning algorithm flow chart of CNN-RELM. CNN-RELM is divided into two parts: CNN and RELM. The related parameters in CNN are adjusted by the gradient descent method according to the errors between the actual output and the expected output. The training process stops if the minimum error reaches or the maximum number of iterations reaches. Then the main part of the CNN is fixed except that the full-connected layer of the CNN is replaced by RELM. The optimal risk ratio parameters γ in the RELM are optimized by genetic algorithm. The Convolution Neural Network (CNN) algorithm is a type of deep learning model primarily used for image recognition, classification, and computer vision tasks. CNNs are inspired by the human visual system and are designed to automatically detect patterns, edges, and features in images(Fig.1.1).

The convolution layer is basically used for the feature extraction. It does the feature extraction by firstly applying convolution function and then activation function on the output of convolution function. There are multiple numbers of convolution layers which are used for the feature extraction.

In the convolution operation, we use a linear function known as the kernel function to extract the features. This kernel function is also known as the filter.

1. CNN Algorithms

Suppose we have an input image described by tensor I of dimension $m_1 \times m_2 \times m_c$. Where,

$$y(i, j) = (x * w)(i, j) = \sum_m \sum_n x(i + m, j + n) \cdot w(m, n) \dots\dots\dots(1)$$

where:

- $Y(i, j)$ is the output feature map at position (i, j)
- $X(i + m, j + n)$ is the input image or previous layer's feature map at position $(i + m, j + n)$
- $W(m, n)$ is the filter (kernel) at position (m, n) .
- b is the bias term.
- M and N are the dimensions of the filter (kernel).

2. Activation Function

After the convolution operation, an activation function is typically applied to introduce non-linearity. One common activation function is the ReLU (Rectified Linear Unit), defined as:

$$F(x) = \text{Max}(0, x) \dots\dots\dots(2)$$

Where x is the input value (could be the result of the convolution).

3. Pooling Layer

The pooling operation is usually applied after the convolution and activation. Max pooling is commonly used, and its formula is:

$$Y(i, j) = \max(X(i, j), X(i + 1, j), X(i, j + 1), X(i + 1, j + 1)) \dots\dots(3)$$

Where:

- $Y(i, j)$ is the output after pooling at position (i, j) .
- $X(i, j)$ represent the input data which are coming from outside.

4. Fully Connected Layer

- After the convolution and pooling layers, the feature maps are flattened and passed through one or more fully connected layers. The output of a fully connected layer is calculated using:

$$Y = W \cdot x + b \dots\dots\dots(4)$$

Where:

Layer (type)	Output Shape	Param #
=====		
conv1d (Conv1D)	(None, 72, 64)	448
batch_normalization (Batch Normalization)	(None, 72, 64)	256
max_pooling1d (MaxPooling1D)	(None, 36, 64)	0
conv1d_1 (Conv1D)	(None, 36, 64)	24640
batch_normalization_1 (Batch Normalization)	(None, 36, 64)	256
max_pooling1d_1 (MaxPooling1D)	(None, 18, 64)	0
conv1d_2 (Conv1D)	(None, 18, 64)	24640
batch_normalization_2 (Batch Normalization)	(None, 18, 64)	256
max_pooling1d_2 (MaxPooling1D)	(None, 9, 64)	0
flatten (Flatten)	(None, 576)	0
dense (Dense)	(None, 64)	36928
dense_1 (Dense)	(None, 64)	4160
dense_2 (Dense)	(None, 3)	195
Total params: 91,779		
Trainable params: 91,395		
Non-trainable params: 384		

Epoch 77/80

have played an integral role in shaping the outcome of this work. We are thankful for the opportunity to contribute to the scholarly community.

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